

# Knowledge Graphs, Description Logics and Reasoning on Data : Reading

Pinpointing in the Description Logic  $\mathcal{EL}$

Théo Delemazure

Ecole normale supérieure, PSL University

April 9, 2020

# The pinpointing problem

Why a certain consequence holds?

## SNOMED CT

Amputation-of-finger  $\sqsubseteq$  Amputation-of-arm

# The pinpointing problem

**Goal of pinpointing** : Find the minimal subset of a Knowledge base that have a given consequence.

Some papers explain an algorithm for pinpointing in  $\mathcal{ALC}$  using an adaptation of the Tableau algorithm.

$\Rightarrow$  What about the inexpressive description logic  $\mathcal{EL}$ ?

# Pinpointing in the Description Logic $\mathcal{EL}$

Authors

*Franz Baader  
Rafael Penaloza,  
and Boontawe  
Suntisrivaraporn*

Year

2007

Workshop

*Description Logics*

Citations

172 to this day

## Pinpointing in the Description Logic $\mathcal{EL}$

Franz Baader<sup>1</sup>, Rafael Penaloza<sup>2\*</sup>, and Boontawe Suntisrivaraporn<sup>1</sup>

<sup>1</sup> Theoretical Computer Science, TU Dresden, Germany  
[baader,msung]@cs.tu-dresden.de

<sup>2</sup> Intelligent Systems, University of Leipzig, Germany  
penaloza@informatik.uni-leipzig.de

### 1. Introduction

For a developer or user of a DL-based ontology, it is often quite hard to understand why a certain consequence holds, and even harder to decide how to change the ontology to cause the consequence to disappear. For example, in the current version of the medical ontology SNOMED [16], the concept *Angiomyolipoma of Pancreas* is classified as a subconcept of *Angiomyolipoma of Arteries*. Finding the axioms that are responsible for this among the more than 300,000 terminological axioms of SNOMED without support by an automated reasoning tool is not easy.

As a first step towards providing such support, Schlobach and Curiat [14] describe an algorithm for computing all the minimal subsets of a given knowledge base that have a given consequence. In the following, we call such a set a *minimal subset* or (*MSU*). It helps the user to comprehend why a certain consequence holds. The knowledge base considered in [14] are so-called *unstable ACC terminologies*, and the unwanted consequences are the *unstability of concepts*. The algorithm is an extension of the known tableau-based satisfiability algorithm for ACC [15], where labels keep track of which axioms are responsible for an assertion to be generated during the run of the algorithm. The authors also run the name “axiom pinpointing” for the task of computing these minimal subsets.

The problem of computing MSUs of DL knowledge base was actually mentioned earlier in the context of extending DLs by default rules. In [2], Baader and Hollander solve this problem by introducing a labeled extension of the tableau-based consistency algorithm for ACC-Allogms [9], which is very similar to the one described later in [14]. The main difference is that the algorithm described in [2] does not directly compute minimal subsets that have a consequence, but rather a *maximally Boolean formula* whose variables correspond to the axioms of the knowledge base and whose minimal satisfying valuations correspond to the MSUs.

The approach of Schlobach and Curiat [14] was extended by Dumas et al. [12] to more expressive DLs, and the one of Baader and Hollander [2] was extended by Meyer et al. [11] to the case of ACC-terminologies with general concept inclusions (GCI), which are no longer satisfiable. Axom pinpointing has also been considered in other research areas, though usually not under this name.

\* Funded by the German Research Foundation (DFG) under grant GRK 485.

# Summary

- 1 Reminder and Definition
  - The  $\mathcal{EL}$  description logic
  - Subsumption in  $\mathcal{EL}$
  - The pinpointing Problem
- 2 Pinpointing Algorithm
  - Computing the pinpointing formula
  - Complexity
  - A more practical algorithm
- 3 Conclusion

# Summary

- 1 Reminder and Definition
  - The  $\mathcal{EL}$  description logic
  - Subsumption in  $\mathcal{EL}$
  - The pinpointing Problem
- 2 Pinpointing Algorithm
  - Computing the pinpointing formula
  - Complexity
  - A more practical algorithm
- 3 Conclusion

Reminder :  $\mathcal{EL}$ 

$$C_1 \sqcap C_2$$

$$\exists r.C$$

$$\top$$

Reminder :  $\mathcal{EL}$  normal form

$$A_1 \sqcap \dots \sqcap A_n \sqsubseteq B$$

$$A \sqsubseteq \exists r.B$$

$$\exists r.A \sqsubseteq B$$

$\Rightarrow$  The normalization can be done in **linear time**.



# Example

The following TBox is in normal form :

$$\{ax_1 : A \sqsubseteq \exists r.A,$$
$$ax_2 : A \sqsubseteq Y,$$
$$ax_3 : \exists r.Y \sqsubseteq B,$$
$$ax_4 : Y \sqsubseteq B\}$$

# Reminder : Subsumption in $\mathcal{EL}$

$\mathcal{A}$  is a **set of assertions** :

$$(A, B) \in \mathcal{A} \Leftrightarrow A \sqsubseteq_{\mathcal{T}} B$$
$$(A, r, B) \in \mathcal{A} \Leftrightarrow A \sqsubseteq_{\mathcal{T}} \exists r.B$$

**Initialization** :  $\forall A,$

$$(A, \top) \in \mathcal{A}$$

$$(A, A) \in \mathcal{A}$$

# Reminder : Subsumption in $\mathcal{EL}$

## The rules :

- If**  $A_1 \sqcap \dots \sqcap A_n \sqsubseteq B \in \mathcal{T}$     **and**  $\forall i, (X, A_i) \in \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$   
**If**  $A \sqsubseteq \exists r.B \in \mathcal{T}$     **and**  $(X, A) \in \mathcal{A}$     **then** add  $(X, r, B)$  to  $\mathcal{A}$   
**If**  $\exists r.A \sqsubseteq B \in \mathcal{T}$     **and**  $\{(X, r, Y), (Y, A)\} \subseteq \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$

**Stop** when no new assertion can be added into  $\mathcal{A}$ .

# Example

$$\{A \sqsubseteq \exists r.A, A \sqsubseteq Y, \exists r.Y \sqsubseteq B, Y \sqsubseteq B\}$$

**If**  $A_1 \sqcap \dots \sqcap A_n \sqsubseteq B \in \mathcal{T}$     **and**  $\forall i, (X, A_i) \in \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$   
**If**  $A \sqsubseteq \exists r.B \in \mathcal{T}$     **and**  $(X, A) \in \mathcal{A}$     **then** add  $(X, r, B)$  to  $\mathcal{A}$   
**If**  $\exists r.A \sqsubseteq B \in \mathcal{T}$     **and**  $\{(X, r, Y), (Y, A)\} \subseteq \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$

**Init** :  $\mathcal{A} = \{(A, \top), (B, \top), (Y, \top), (A, A), (B, B), (Y, Y)\}$

# Example

$$\{A \sqsubseteq \exists r.A, A \sqsubseteq Y, \exists r.Y \sqsubseteq B, Y \sqsubseteq B\}$$

**If**  $A_1 \sqcap \dots \sqcap A_n \sqsubseteq B \in \mathcal{T}$     **and**  $\forall i, (X, A_i) \in \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$   
**If**  $A \sqsubseteq \exists r.B \in \mathcal{T}$     **and**  $(X, A) \in \mathcal{A}$     **then** add  $(X, r, B)$  to  $\mathcal{A}$   
**If**  $\exists r.A \sqsubseteq B \in \mathcal{T}$     **and**  $\{(X, r, Y), (Y, A)\} \subseteq \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$

$$\mathcal{A} = \{(A, \top), (B, \top), (Y, \top), (A, A), (B, B), (Y, Y), (A, r, A)\}$$

# Example

$$\{A \sqsubseteq \exists r.A, A \sqsubseteq Y, \exists r.Y \sqsubseteq B, Y \sqsubseteq B\}$$

**If**  $A_1 \sqcap \dots \sqcap A_n \sqsubseteq B \in \mathcal{T}$     **and**  $\forall i, (X, A_i) \in \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$   
**If**  $A \sqsubseteq \exists r.B \in \mathcal{T}$     **and**  $(X, A) \in \mathcal{A}$     **then** add  $(X, r, B)$  to  $\mathcal{A}$   
**If**  $\exists r.A \sqsubseteq B \in \mathcal{T}$     **and**  $\{(X, r, Y), (Y, A)\} \subseteq \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$

$$\mathcal{A} = \{(A, \top), (B, \top), (Y, \top), (A, A), (B, B), (Y, Y), (A, r, A), (A, B)\}$$

And so on...

# Example

$$\{A \sqsubseteq \exists r.A, A \sqsubseteq Y, \exists r.Y \sqsubseteq B, Y \sqsubseteq B\}$$

**If**  $A_1 \sqcap \dots \sqcap A_n \sqsubseteq B \in \mathcal{T}$     **and**  $\forall i, (X, A_i) \in \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$   
**If**  $A \sqsubseteq \exists r.B \in \mathcal{T}$     **and**  $(X, A) \in \mathcal{A}$     **then** add  $(X, r, B)$  to  $\mathcal{A}$   
**If**  $\exists r.A \sqsubseteq B \in \mathcal{T}$     **and**  $\{(X, r, Y), (Y, A)\} \subseteq \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$

$$\mathcal{A} = \{(A, \top), (B, \top), (Y, \top), (A, A), (B, B), (Y, Y), (A, r, A), (A, B)\}$$

And so on...

# The pinpointing Problem : minAs

## Definition

A **minA** for a TBox  $\mathcal{T}$  with respect to  $A \sqsubseteq B$  is a subset  $\mathcal{S}$  of  $\mathcal{T}$  s.t.  $A \sqsubseteq_{\mathcal{S}} B$  but  $A \not\sqsubseteq_{\mathcal{S}'} B$  for all  $\mathcal{S}' \subset \mathcal{S}$ .

Problem : How to find one minA? How to find all minAs?



# The pinpointing Problem : minAs

## Definition

A **minA** for a TBox  $\mathcal{T}$  with respect to  $A \sqsubseteq B$  is a subset  $\mathcal{S}$  of  $\mathcal{T}$  s.t.  $A \sqsubseteq_{\mathcal{S}} B$  but  $A \not\sqsubseteq_{\mathcal{S}'} B$  for all  $\mathcal{S}' \subset \mathcal{S}$ .

Problem : How to find **one** minA? How to find **all** minAs?

# The pinpointing Problem : Pinpointing formula

Let's assume each CGI  $t \in \mathcal{T}$  is labeled  $lab(t) \in lab(\mathcal{T})$ . A **monotone Boolean formula** over  $lab(\mathcal{T})$  is a Boolean formula using variables in  $lab(\mathcal{T})$ , conjunctions, disjunctions and True.

## Definition

A **pinpointing formula** for a TBox  $\mathcal{T}$  with respect to  $A \sqsubseteq B$  is a monotone Boolean  $\phi$  formula over  $lab(\mathcal{T})$  such that for each valuation  $\mathcal{V} \in lab(\mathcal{T})$

$$A \sqsubseteq_{\mathcal{T}_{\mathcal{V}}} B \Leftrightarrow \mathcal{V} \text{ satisfies } \phi$$

# The pinpointing Problem : Pinpointing formula

Using the pinpointing formula, we can find the minAs. Indeed, if  $\phi$  is a **pinpointing formula** for  $\mathcal{T}$  with respect to  $A \sqsubseteq B$  then **the set of all MinAs** for  $\mathcal{T}$  with respect to  $A \sqsubseteq B$  is :

$$\{ \mathcal{T}_{\mathcal{V}} \mid \mathcal{V} \text{ is a minimal valuation satisfying } \phi \}$$

$\Rightarrow$  To compute MinAs, it is enough to find a pinpointing formula. However, this may cause an exponential blowup in the number of variables.

# Example

$$\{ax_1 : A \sqsubseteq \exists r.A, ax_2 : A \sqsubseteq Y, ax_3 : \exists r.Y \sqsubseteq B, ax_4 : Y \sqsubseteq B\}$$

In this example, the **minAs** of  $\mathcal{T}$  with respect to  $A \sqsubseteq B$  are  $\{ax_2, ax_4\}$  and  $\{ax_1, ax_2, ax_3\}$ .

Therefore, a **pinpointing formula** is  $ax_2 \wedge (ax_4 \vee (ax_1 \wedge ax_3))$ .

# Summary

- 1 Reminder and Definition
  - The  $\mathcal{EL}$  description logic
  - Subsumption in  $\mathcal{EL}$
  - The pinpointing Problem
- 2 Pinpointing Algorithm
  - Computing the pinpointing formula
  - Complexity
  - A more practical algorithm
- 3 Conclusion

# Computing the pinpointing formula

**Init** : assertions  $(A, \top)$  and  $(A, A)$  receive label  $\tau$ .

**If**  $A_1 \sqcap \dots \sqcap A_n \sqsubseteq B \in \mathcal{T}$     **and**  $\forall i, (X, A_i) \in \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$   
**If**  $A \sqsubseteq \exists r. B \in \mathcal{T}$     **and**  $(X, A) \in \mathcal{A}$     **then** add  $(X, r, B)$  to  $\mathcal{A}$   
**If**  $\exists r. A \sqsubseteq B \in \mathcal{T}$     **and**  $\{(X, r, Y), (Y, A)\} \subseteq \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$

- 1 Let  $\phi$  be the conjunction of labels of the CGIs from  $\mathcal{T}$  and the assertions from  $\mathcal{A}$  used in the rule.
- 2 If the assertion in the consequence does not yet belong to  $\mathcal{A}$ , add it with label  $\phi$ .
- 3 Otherwise, if  $\psi$  is the label of the assertion in the consequence and  $\psi \not\# \phi$ , then replace the label of this assertion by  $\psi \vee \phi$ .

# Example

$$\{A \sqsubseteq \exists r.A, A \sqsubseteq Y, \exists r.Y \sqsubseteq B, Y \sqsubseteq B\}$$

**If**  $A_1 \sqcap \dots \sqcap A_n \sqsubseteq B \in \mathcal{T}$     **and**  $\forall i, (X, A_i) \in \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$   
**If**  $A \sqsubseteq \exists r.B \in \mathcal{T}$     **and**  $(X, A) \in \mathcal{A}$     **then** add  $(X, r, B)$  to  $\mathcal{A}$   
**If**  $\exists r.A \sqsubseteq B \in \mathcal{T}$     **and**  $\{(X, r, Y), (Y, A)\} \subseteq \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$

**Init :**

$$\mathcal{A} = \{(A, \top, \mathbf{t}), (B, \top, \mathbf{t}), (Y, \top, \mathbf{t}), (A, A, \mathbf{t}), (B, B, \mathbf{t}), (Y, Y, \mathbf{t})\}$$

# Example

$$\{A \sqsubseteq \exists r.A, A \sqsubseteq Y, \exists r.Y \sqsubseteq B, Y \sqsubseteq B\}$$

**If**  $A_1 \sqcap \dots \sqcap A_n \sqsubseteq B \in \mathcal{T}$     **and**  $\forall i, (X, A_i) \in \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$   
**If**  $A \sqsubseteq \exists r.B \in \mathcal{T}$     **and**  $(X, A) \in \mathcal{A}$     **then** add  $(X, r, B)$  to  $\mathcal{A}$   
**If**  $\exists r.A \sqsubseteq B \in \mathcal{T}$     **and**  $\{(X, r, Y), (Y, A)\} \subseteq \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$

$$\mathcal{A} = \{(A, \top, \mathfrak{t}), (B, \top, \mathfrak{t}), (Y, \top, \mathfrak{t}), (A, A, \mathfrak{t}), (B, B, \mathfrak{t}), (Y, Y, \mathfrak{t}), (A, r, A, ax_1)\}$$



# Example

$$\{A \sqsubseteq \exists r.A, A \sqsubseteq Y, \exists r.Y \sqsubseteq B, Y \sqsubseteq B\}$$

**If**  $A_1 \sqcap \dots \sqcap A_n \sqsubseteq B \in \mathcal{T}$     **and**  $\forall i, (X, A_i) \in \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$   
**If**  $A \sqsubseteq \exists r.B \in \mathcal{T}$     **and**  $(X, A) \in \mathcal{A}$     **then** add  $(X, r, B)$  to  $\mathcal{A}$   
**If**  $\exists r.A \sqsubseteq B \in \mathcal{T}$     **and**  $\{(X, r, Y), (Y, A)\} \subseteq \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$

$$\mathcal{A} = \{(A, \top, \mathbf{t}), (B, \top, \mathbf{t}), (Y, \top, \mathbf{t}), (A, A, \mathbf{t}), (B, B, \mathbf{t}), (Y, Y, \mathbf{t}), \\ (A, r, A, ax_1), (A, B, ax_1 \wedge ax_2 \wedge ax_3)\}$$

And so on...

# Example

$$\{A \sqsubseteq \exists r.A, A \sqsubseteq Y, \exists r.Y \sqsubseteq B, Y \sqsubseteq B\}$$

**If**  $A_1 \sqcap \dots \sqcap A_n \sqsubseteq B \in \mathcal{T}$     **and**  $\forall i, (X, A_i) \in \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$   
**If**  $A \sqsubseteq \exists r.B \in \mathcal{T}$     **and**  $(X, A) \in \mathcal{A}$     **then** add  $(X, r, B)$  to  $\mathcal{A}$   
**If**  $\exists r.A \sqsubseteq B \in \mathcal{T}$     **and**  $\{(X, r, Y), (Y, A)\} \subseteq \mathcal{A}$     **then** add  $(X, B)$  to  $\mathcal{A}$

$$\mathcal{A} = \{(A, \top, \mathbf{t}), (B, \top, \mathbf{t}), (Y, \top, \mathbf{t}), (A, A, \mathbf{t}), (B, B, \mathbf{t}), (Y, Y, \mathbf{t}), \\ (A, r, A, ax_1), (A, B, ax_1 \wedge ax_2 \wedge ax_3)\}$$

And so on...

# Computing the pinpointing formula : Termination

This algorithm always terminate

- The number of assertion is finite.
- The number of accepting valuation for the label of each assertion only increase (since we always do a disjunction) and there is a finite number of monotone Boolean formula over  $lab(\mathcal{T})$ .

# Computing the pinpointing formula : Correctness

This algorithm return every valid assertion in  $\mathcal{T}$ , with a valid pinpointing formula

- The first part is true, since the final set  $\mathcal{A}$  is the same than the one in the original algorithm.
- The second point is not proven in the paper, but we can see that it is possible to do it by induction.

# General case

Note that the algorithm we described only works for **normalized TBoxes**.

However, we can replace every label of the normalized TBox with the disjunction of its possible sources.

# General case

Note that the algorithm we described only works for **normalized TBoxes**.

However, we can replace every label of the normalized TBox with the disjunction of its possible sources.

# Computing one MinA : Algorithm

- 1 If  $A \not\sqsubseteq_{\mathcal{T}} B$ , then return **no MinA**.
- 2 Initialize  $\mathcal{S} := \mathcal{T}$ .
- 3 For  $i \in [1, n]$ , if  $A \sqsubseteq_{\mathcal{S} \setminus \{t_i\}} B$ , then  $t_i$  is not necessary and we can set

$$\mathcal{S} \leftarrow \mathcal{S} \setminus \{t_i\}$$

- 4 The resulting set  $\mathcal{S}$  is a **MinA**.

$\Rightarrow$  Take **polynomial time**

# Computing all MinAs : Complexity

$$\mathcal{T}_n := \{B_{i-1} \sqsubseteq P_i \sqcap Q_i, P_i \sqsubseteq B_i, Q_i \sqsubseteq B_i \mid 1 \leq i \leq n\}$$

Each MinA for  $\mathcal{T}_n$  with respects to  $B_0 \sqsubseteq B_n$  contains either  $P_i \sqsubseteq B_i$  or  $Q_i \sqsubseteq B_i$ . Therefore, there is  $2^n$  MinAs.

$\Rightarrow$  More generally, the problem of finding if there is a MinA of cardinality  $\leq n$  is **NP-complete** (by reduction of the *hitting set Problem*).



In practice...

# SNOMED CT

contains more than 350,000 axioms

⇒ Algorithm for one MinA is impractical....

...Hopefully, we can improve it by first computing a greedy subset of  $\mathcal{T}$  from which the subsumption follows, and initialize  $S$  to it.

In practice...

# SNOMED CT

contains more than 350,000 axioms

⇒ Algorithm for one MinA is impractical....

...Hopefully, we can improve it by first computing a greedy subset of  $\mathcal{T}$  from which the subsumption follows, and initialize  $\mathcal{S}$  to it.

# Improved algorithm

- 1 Let  $\phi$  be the conjunction of labels of the CGIs from  $\mathcal{T}$  and the assertions from  $\mathcal{A}$  used in the rule.
- 2 If the assertion in the consequence does not yet belong to  $\mathcal{A}$ , add it with label  $\phi$ .
- 3 ~~Otherwise, if  $\psi$  is the label of the assertion in the consequence and  $\psi \not\vdash \phi$ , then replace the label of this assertion by  $\psi \vee \phi$ .~~

$\Rightarrow$  Back to polynomial time, but the final subset for each assertion is **not minimal**.

+ Use of a greedy strategy to go from a non normalized TBox to a normalized one.

# Improved algorithm

- 1 Let  $\phi$  be the conjunction of labels of the CGIs from  $\mathcal{T}$  and the assertions from  $\mathcal{A}$  used in the rule.
- 2 If the assertion in the consequence does not yet belong to  $\mathcal{A}$ , add it with label  $\phi$ .
- 3 ~~Otherwise, if  $\psi$  is the label of the assertion in the consequence and  $\psi \not\vdash \phi$ , then replace the label of this assertion by  $\psi \vee \phi$ .~~

$\Rightarrow$  Back to polynomial time, but the final subset for each assertion is **not minimal**.

+ Use of a greedy strategy to go from a non normalized TBox to a normalized one.

# Experiments

The logo for Galen Medical Group features the word "GALEN" in a large, white, serif font. A laurel wreath is positioned behind the letter "A". Below "GALEN", the words "MEDICAL GROUP" are written in a smaller, white, sans-serif font. The entire logo is centered on a dark blue rectangular background.

GALEN  
MEDICAL GROUP

4,000 axioms

# Experiments

Subsumption algorithm to find the 27,000 subsumption relationships	14 s
Modified pinpointing algorithm	23 s
Going from normalized TBox to non normalized one	0.27 s
Finding one MinA (optimized)	9 : 45 min
Finding one MinA	7 hours

# Experiments

- The **average size** of the set of axioms before minimizing it with algorithm 1 is 5, which is enough to give an understandable explanation to the user.
- The final set where **almost minimal**, and the non-minimal sets were in average 2.59% larger than the minimal ones.

# Summary

- 1 Reminder and Definition
  - The  $\mathcal{EL}$  description logic
  - Subsumption in  $\mathcal{EL}$
  - The pinpointing Problem
- 2 Pinpointing Algorithm
  - Computing the pinpointing formula
  - Complexity
  - A more practical algorithm
- 3 Conclusion



# Conclusion

- 1 The authors propose a PTIME algorithm to **compute one MinA** in the description logic  $\mathcal{EL}$ .
- 2 They show that the problem of **finding all MinAs** need exponential time.
- 3 They propose **a practical algorithm** to find an almost minimal explanation and show that this algorithm gives nice results.

# Limits and comments

- In the Algorithm to compute one  $\text{MinA}$ , it is **not clear** where the computation of the pinpointing formula is used and where it is used ?
- **The practical section** is very interesting, maybe a few more experiments (other base), a nice table to show the results, and a better description of the framework would have been great.
- Due to length constraints, some proofs (of validity or termination for instance) are overflowed.

## Further work

### What can be done next ?

- Find pinpointing procedures on **other DL** and maybe try to generalize it. *Axiom pinpointing in general tableaux* (2010)
- Instead of computing minimal sets which have a given consequence, why not compute **maximal sets that do not have** a given consequence. We have theoretical results, but not a practical algorithm like here.
- Do more practical experiments and try to optimize the algorithm presented. *Debugging SNOMED CT using axiom pinpointing in the description logic EL* (2008)
- Apply this to OWL for instance. *Explaining inconsistencies in OWL ontologies* (2009)

# Thanks for your attention !