Reallocating Wasted Votes in Proportional Parliamentary Elections with Thresholds

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Joint work with Rupert Freeman, Jérôme Lang, Jean-François Laslier and Dominik Peters (published at EC-2025)

1. Computational Social Choice

What is social choice?

Social Choice Theory:

Designing and analyzing methods for collective decision making



Political election

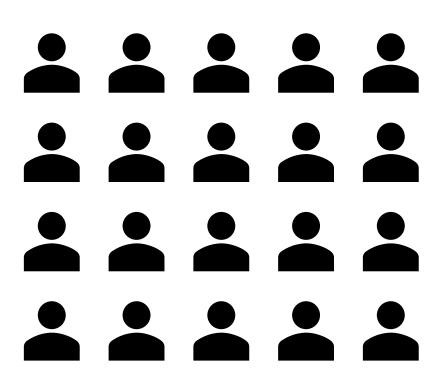


Decide on a date

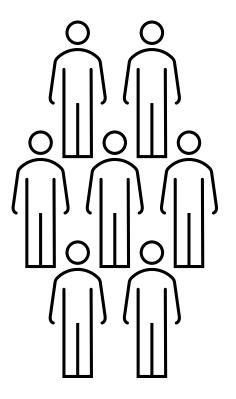


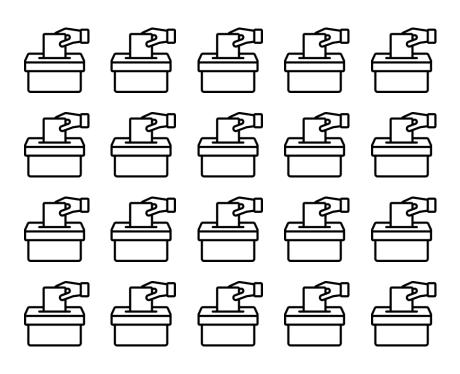
Jury decision

Voters

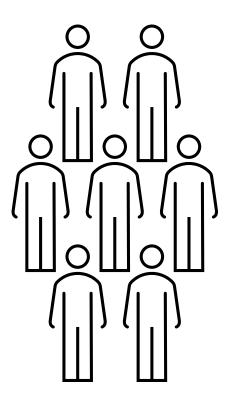


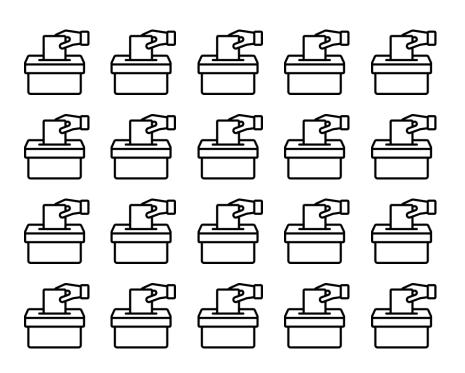
Candidates



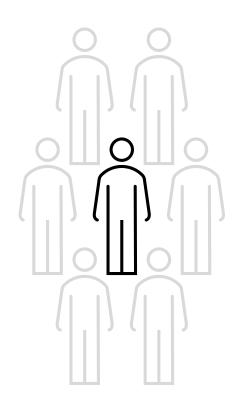


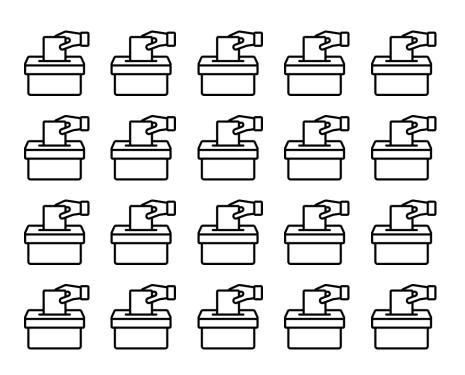
Candidates



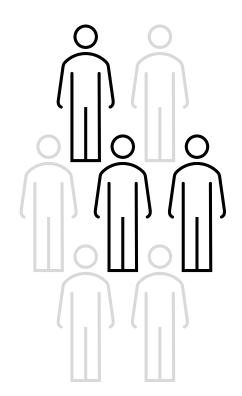


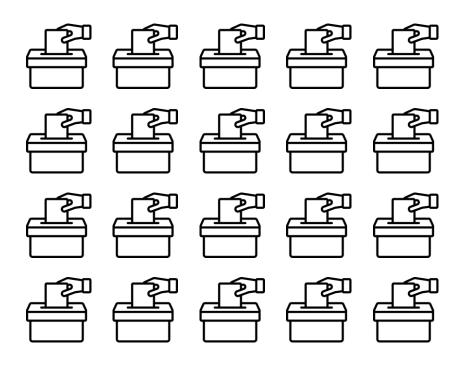
A winner is selected



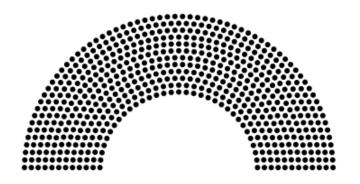


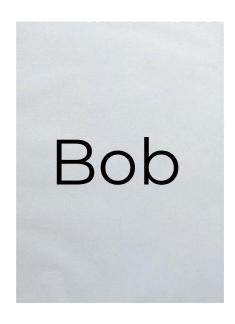
A **committee** is selected





A parliament is selected





Uninominal Ballots

Ballot formats

Bob

Uninominal Ballots

1 Bob

2 Ann

3 Dan

4 Cora

Rankings

Ann

✓ Bob

✓ Cora

Dan

Approval Ballots

Bob 5

Ann 2

Dan 3

Cora 3

Scores

2. Single-winner voting with rankings

We have:

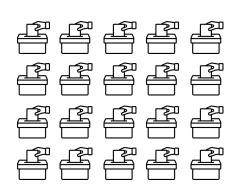
- A set of **voters** $V = \{1, 2, ..., n\}$.
- A set of candidates $C = \{c_1, ..., c_m\}$.
- A preference **profile** $P = (\succ_1, ..., \succ_n) \in \mathcal{L}(C)^n$ of rankings of voters over candidates.

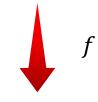
We want:

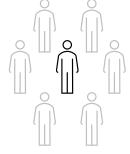
- A winning candidate $w \in C$.

For this, we use:

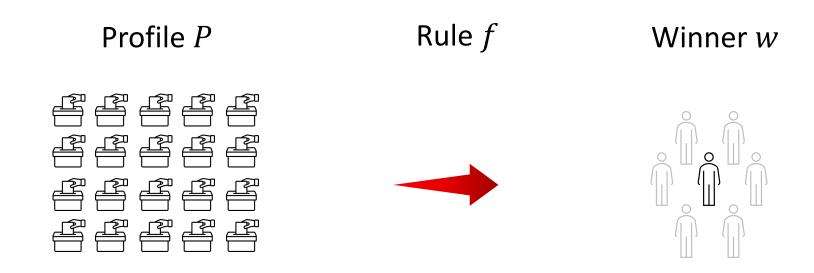
- A voting rule $f: \mathcal{L}(C)^n \to C$.







14



Question: which voting rule should we use?

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- **Design** rules, analyze their complexity, and propose algorithms to compute them.
- Check the **normative properties** (the *axioms*) satisfied by these rules.
- Run simulations of the rules on real or synthetic preference data.

Design rules: *Plurality*

Plurality: The winner is the candidate that is ranked first by the most voters.

40%
$$A > B > D > C$$

25% $B > C > D > A$
20% $C > B > D > A$ Winner: A

15%
$$D > C > A > B$$

Design rules: *Veto*

Veto: The winner is the candidate that is ranked last by the fewest voters.

$$40\% \quad A > B > D > C$$

$$25\%$$
 $B > C > D > A$

$$20\%$$
 $C > B > D > A$

15%
$$D > C > A > B$$



Winner: D

1 Design rules: Borda

Borda: Voters give m-1 points to the first candidate, m-2 to the second, and so on. The winner is the candidate with the highest score.

40%
$$A > B > D > C$$

25% $B > C > D > A$
20% $C > B > D > A$
15% $D > C > A > B$

Design rules: The family of *Scoring rules*



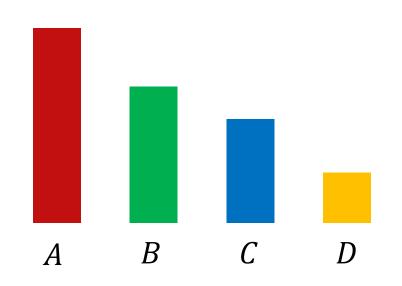
Plurality Borda Veto

Design rules: *Instant Runoff Voting* (IRV/STV)

Instant Runoff Voting (IRV): Repeatedly eliminate the candidate with the fewest 1st-place votes until one candidate gets 50% of the votes.

40%
$$A > B > D > C$$

25% $B > C > D > A$
20% $C > B > D > A$
15% $D > C > A > B$



Design rules: *Instant Runoff Voting* (IRV/STV)

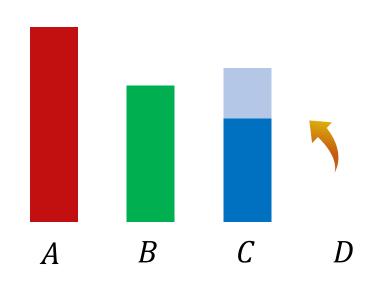
Instant Runoff Voting (IRV): Repeatedly eliminate the candidate with the fewest 1st-place votes until one candidate gets 50% of the votes.

$$40\% \quad A > B > C$$

$$25\%$$
 B > C > A

$$20\%$$
 $C > B > A$

15%
$$C > A > B$$



Design rules: *Instant Runoff Voting* (IRV/STV)

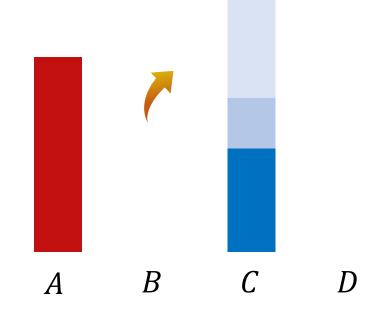
Instant Runoff Voting (IRV): Repeatedly eliminate the candidate with the fewest 1st-place votes until one candidate gets 50% of the votes.

$$40\% \quad A > C$$

25%
$$C > A$$

$$20\%$$
 $C > A$

$$15\%$$
 $C > A$



Check the **normative properties** (the *axioms*).

Axiom: Reinforcement

If a candidate wins in a profile P_1 and in a profile P_2 , it also wins in the profile P_1+P_2 .

Characterization Theorem (Smith and Young, 1973): Scoring Rules are the only voting rules that satisfy reinforcement, neutrality, and anonymity.

Check the **normative properties** (the *axioms*).

Axiom: Strategyproofness

A voter cannot obtain a better winner by misreporting their preferences.

$$4 \times A > B > D > C$$

$$3 \times B > C > A > D$$

$$2 \times C > B > D > A$$

$$2 \times D > C > A > B$$

$$2 \times D > C > A > B$$

$$2 \times D > C > A > B$$

The plurality winner is A.

The plurality winner is now B.

Axiomatic analysis

Check the **normative properties** (the *axioms*).

Axiom: Strategyproofness

A voter cannot obtain a better winner by misreporting their preferences.

Impossibility Theorem (Gibbard and Satterthwaite, 1973): There exists no rule that satisfies strategyproofness, resoluteness, non-imposition and non-dictatorship.

Run simulations with the voting rules.

We need preference data for the simulations:

- Generate **synthetic data** from probabilistic models.
- Use data from **online libraries** of datasets (e.g., Preflib).
- Design **voting experiments** and collect data.

3. Proportional Parliementary elections with Threshold

Voting systems for parliamentary elections







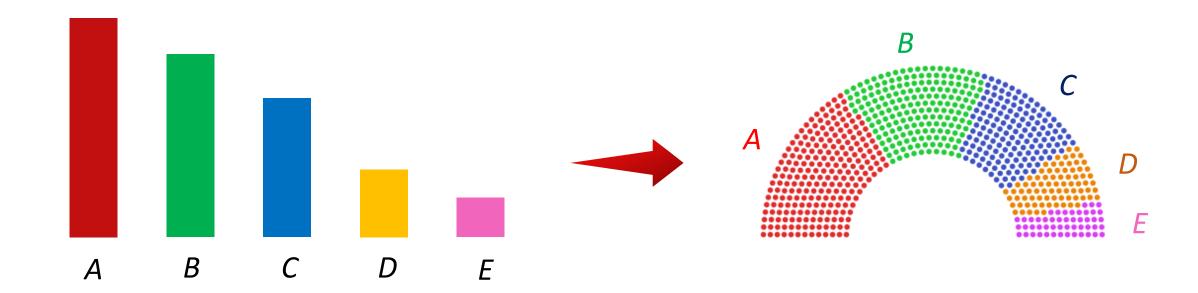






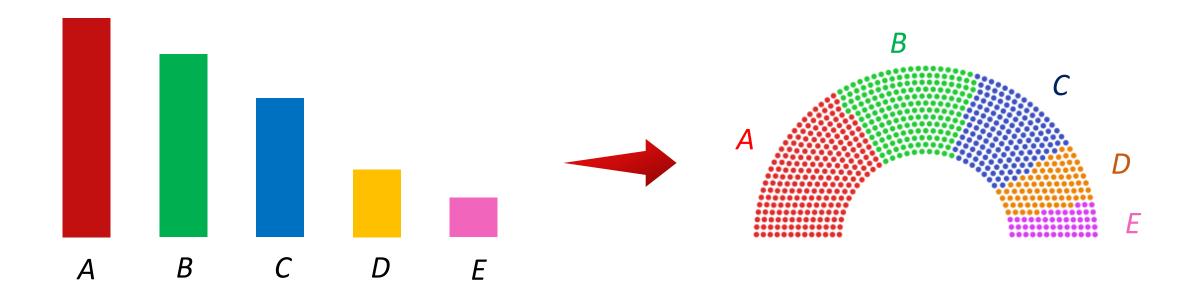
Voters vote for one party.

Seats are allocated to parties proportionally to their scores.



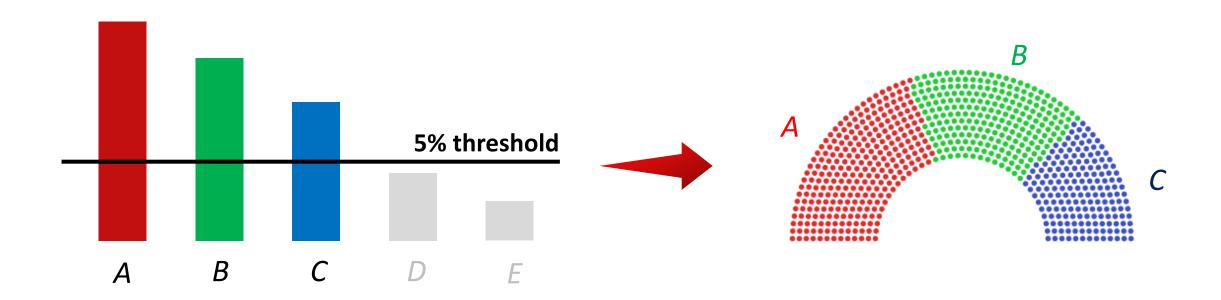
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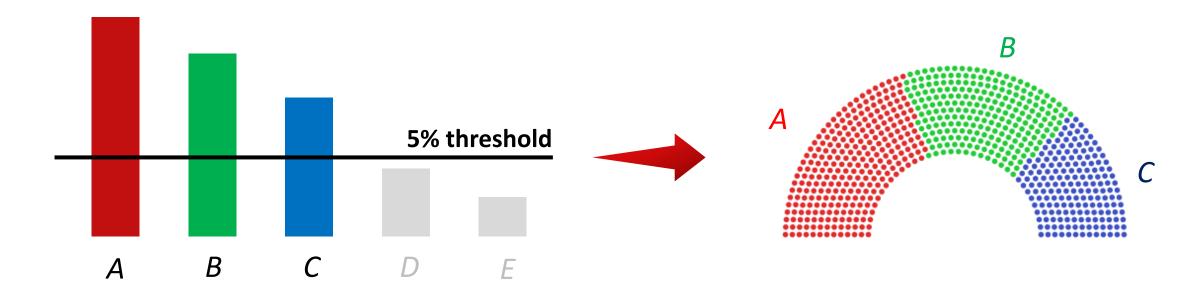
Seats are allocated to parties proportionally to their scores.



Problem: possible political fragmentation (many parties get a seat).

Many countries impose an **electoral threshold** to reduce political fragmentation.





- → Some votes are "lost": D and E supporters have no influence on the seat distribution.
- This incentivizes forms of tactical voting.

The "lost" votes

		Threshold	"Lost" votes
* * * * * * *	2019 election of the French representative to the EU Parliament.	5%	20%
	2025 election of the <i>Bundestag</i> members.	5%	14% increasing in recent decades
C*	2002 election of the <i>Turkish</i> Parliament members.	10%	46%

We could let voters **indicate a second choice** to be used in case their first choice does not reach the threshold.







We could ask voters to rank **two parties**

- 1 Party B
- 2 Party D

We could even ask for a truncated ranking

- 1 Party B
- 2 Party D
- 3 Party A
- 4 Party C

We could ask voters to rank **two parties**

- 1 Party B
- 2 Party D

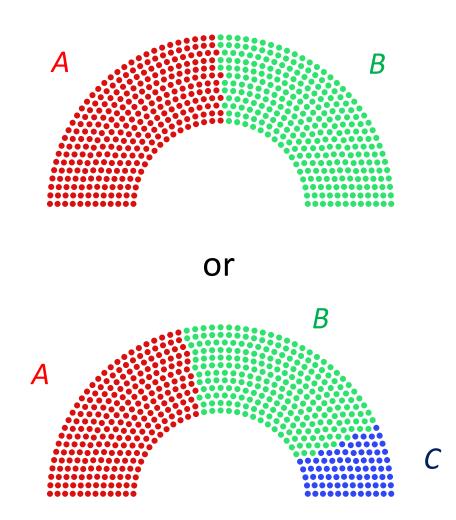
We could even ask for a truncated ranking

- 1 Party B
- 2 Party D
- 3 Party A
- 4 Party C

Question: how to decide which parties are "above the threshold"?

43% A 43% B 4% C > D 2% D > C

5% threshold



We have:

- Sets of voters $V = \{1, 2, ..., n\}$ and parties $C = \{p_1, ..., p_m\}$.
- A preference profile $P = (\succ_1, ..., \succ_n)$ of truncated rankings of voters over parties.
- A given **threshold** τ (absolute number of voters).

We want:

- A set of selected parties $S \subseteq C$, called the **outcome**.
- Voters are represented by their most-preferred party in S (if any).
- An outcome S is **feasible** if every party represents at least τ voters.
- We assume that parties in S get a **number of seats proportional** to the **share** of voters they represent.

$$6 \times A > B > D > C$$
 $4 \times B > C > E > A > D$
 $3 \times C > B$
 $3 \times D > E > B > A > C$

- Threshold $\tau = 5$.

 $2 \times C > A > E$

Outcome $\{A\}$ is feasible.

$$6 \times A > B > D > C$$

$$4 \times B > C > E > A > D$$

$$3 \times C > B$$

$$3 \times D > E > B > A > C$$

$$2 \times C > A > E$$

- Threshold $\tau = 5$.

Outcome $\{A\}$ is feasible.

Outcome $\{E\}$ is feasible.

$$6 \times A > B > D > C$$

$$4 \times B > C > E > A > D$$

$$3 \times C > B$$

$$3 \times D > E > B > A > C$$

$$2 \times C > A > E$$

- Threshold $\tau = 5$.

Outcome $\{A\}$ is feasible.

Outcome $\{E\}$ is feasible.

Outcome $\{A, C\}$ is feasible.

$$6 \times A > B > D > C$$

$$\mathbf{4} \times \mathbf{B} > C > E > A > D$$

$$3 \times C > B$$

$$3 \times D > E > B > A > C$$

$$2 \times C > A > E$$

- Threshold $\tau = 5$.

Outcome $\{A\}$ is feasible.

Outcome $\{E\}$ is feasible.

Outcome $\{A, C\}$ is feasible.

Outcome $\{A, B, C\}$ is feasible.

$$6 \times A > B > D > C$$

$$\mathbf{4} \times \mathbf{B} > C > E > A > D$$

$$3 \times C > B$$

$$3 \times D > E > B > A > C$$

$$2 \times C > A > E$$

- Threshold $\tau = 5$.

Outcome $\{A\}$ is feasible.

Outcome $\{E\}$ is feasible.

Outcome $\{A, C\}$ is feasible.

Outcome $\{A, B, C\}$ is feasible.

Outcome $\{B, D\}$ is not feasible.

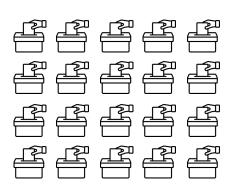
Generalization of single-winner voting

If $\tau > n/2$ and with full rankings, this corresponds to the **single-winner voting model** (if we additionally force a non-empty outcome).

(This is because when $\tau > n/2$, only one candidate can be part of the outcome since each candidate in the outcome needs to represent more than τ voters)

Summary of the problem

Profile *P*



 \bullet Threshold τ

Party Selection Rule f



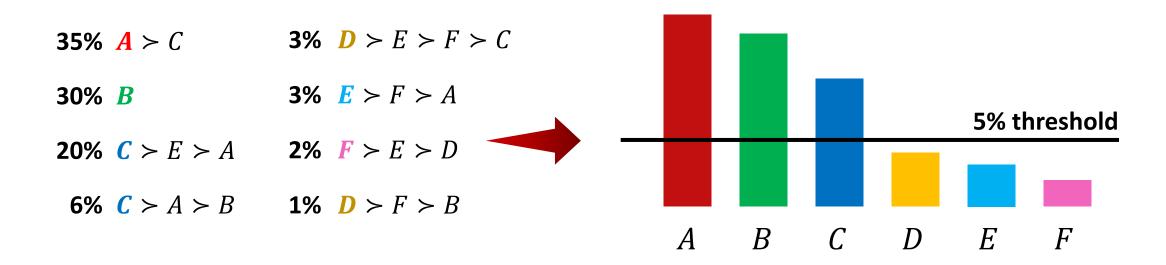
Feasible Outcome

$$S \subseteq C$$

4. Party Selection Rules

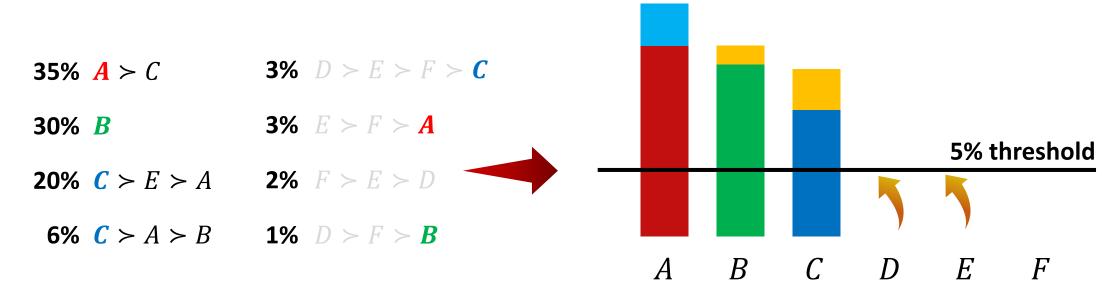
Rule: Direct Winners Only (DO)

The selected parties are all those which receive more first-place votes than required by the threshold.



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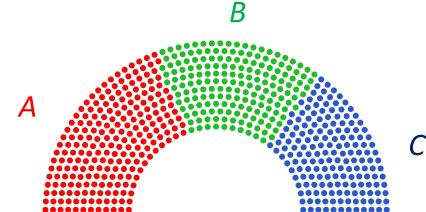
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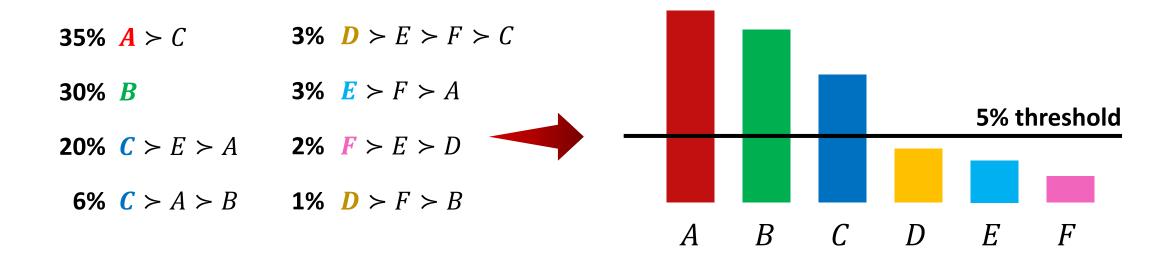
35%
$$A > C$$
 3% $D > E > F > C$

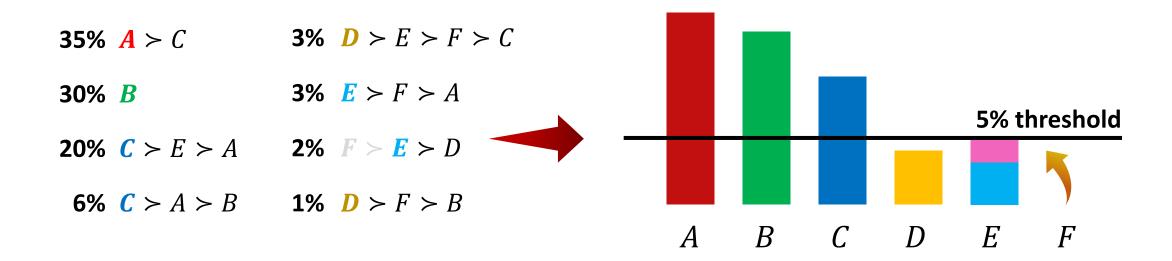
30% B 3% $E > F > A$ A

20% $C > E > A$ 2% $F > E > D$

6% $C > A > B$ 1% $D > F > B$





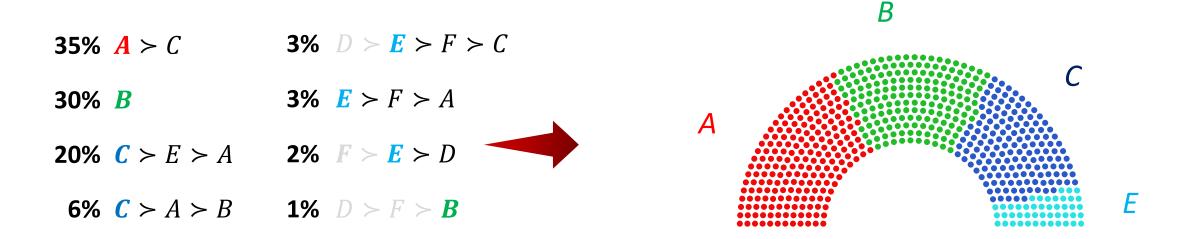


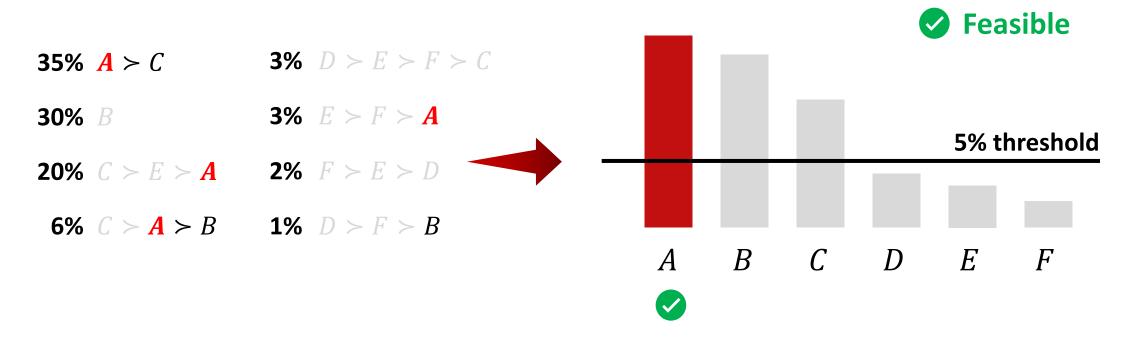
35%
$$A > C$$
 3% $D > E > F > C$

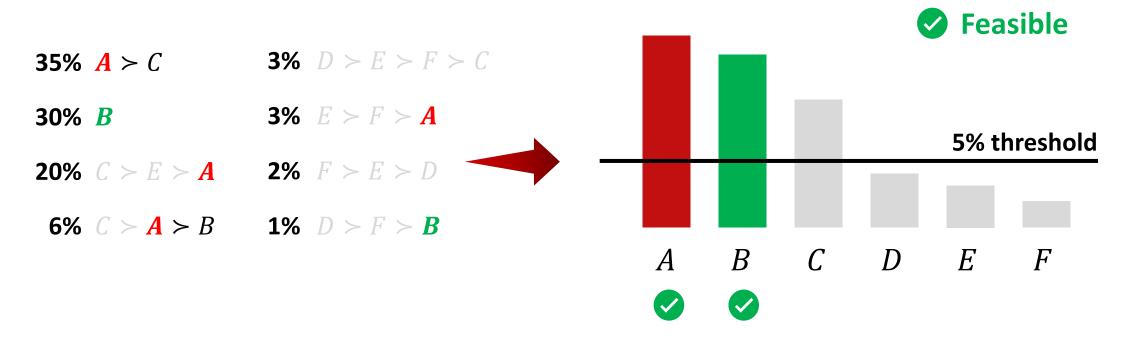
30% B 3% $E > F > A$

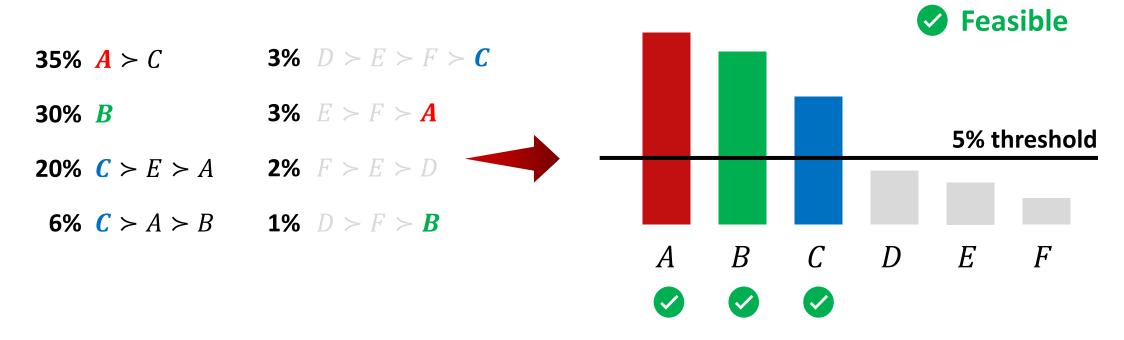
5% threshold

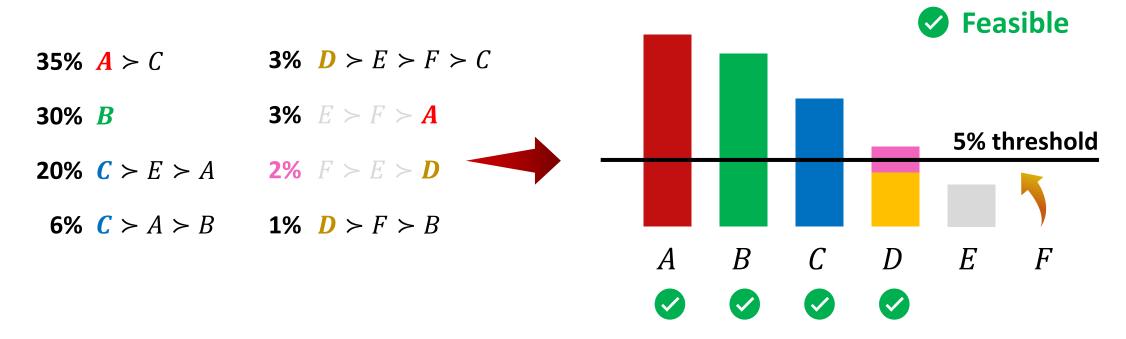
6% $C > A > B$ 1% $D > F > B$
 $A B C D E F$



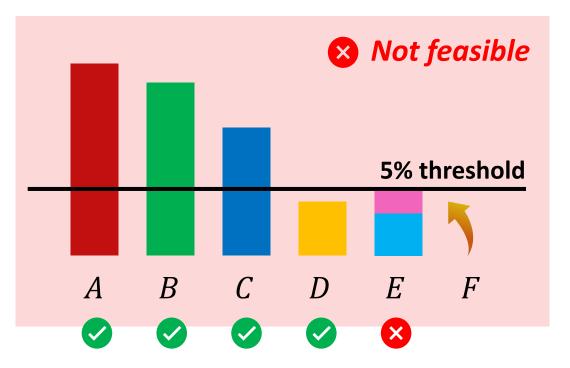




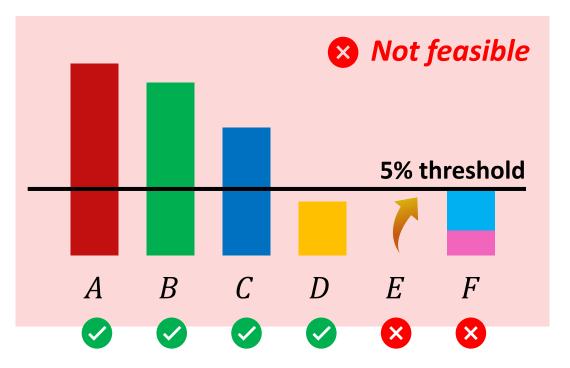


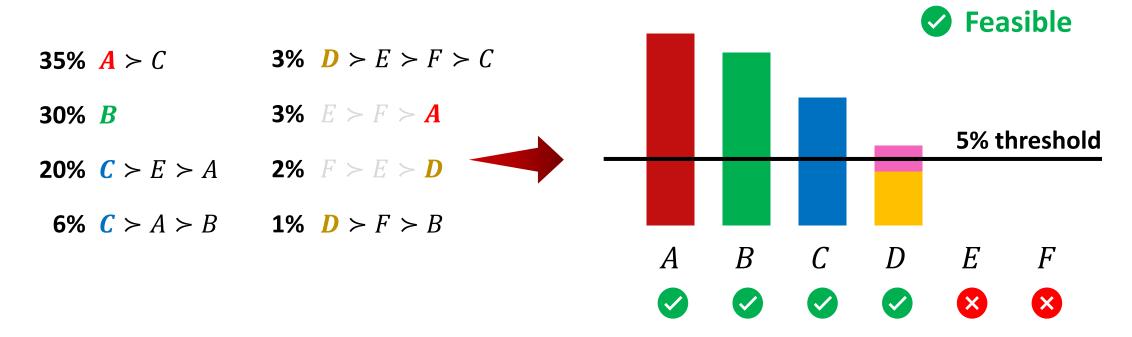


35%
$$A > C$$
 3% $D > E > F > C$
30% B 3% $E > F > A$
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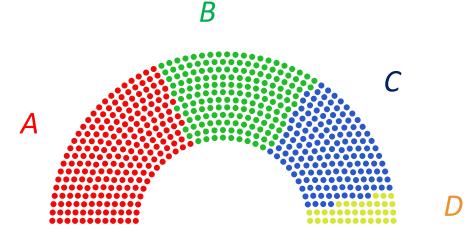


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30% B 3% $E > F > A$

20% $C > E > A$ 2% $F > E > D$

6% $C > A > B$ 1% $D > F > B$



Rule: Maximum Representation (MaxR)

Return the feasible outcome that maximizes the number of voters that are **represented**.

Rule: Maximum Plurality (MaxP)

Return the feasible outcome that maximizes the number of voters that are **represented by their first choice**.

Computational Complexity

Theorem: The outcome of DO, STV and GP can be computed in polynomial time.

Theorem: The problem of computing the outcome of MaxR and MaxP is **NP-hard.**

(proof by reduction to the independent set problem)

5. Axiomatic Analysis

Inclusion of Direct Winners

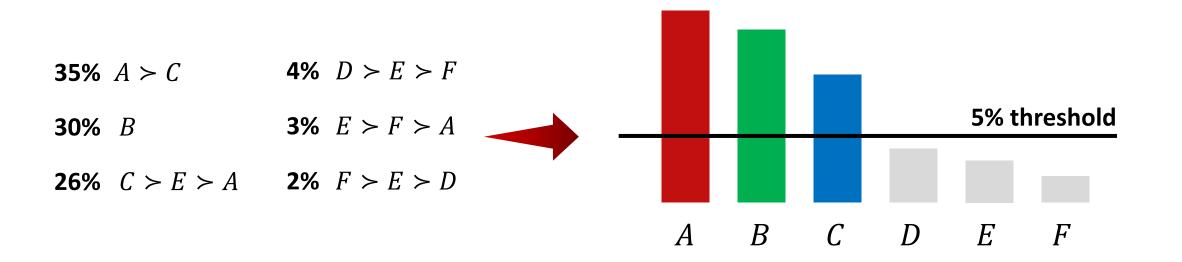
Axiom: Inclusion of Direct Winners

If τ voters or more rank a party x on top of their rankings, this party should be selected.









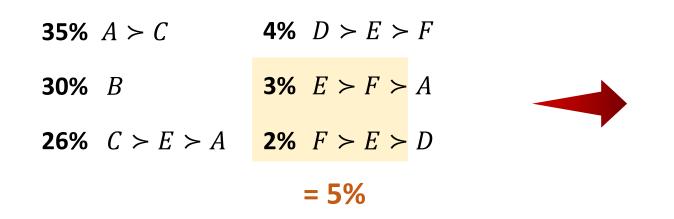
Representation of Solid Coalitions

Axiom: Representation of solid coalitions

If τ voters or more rank a set of parties T on top of their rankings, at least one of these parties should be selected.

Inspired by Proportionality for Solid Coalitions [Dummet 94]





Party E or F should be part of the outcome. **Axiom:** Threshold Monotonicity











If a party is selected for threshold τ , then it is also selected for threshold $\tau' < \tau$.

Axiom: Ind. of Definitely Losing Parties SDO STV SGP MaxP MaxR











Once some parties are losing at some threshold τ , then for all larger thresholds au' > au, the rule should behave as if none of the losing parties had been available.

Characterization Theorem : STV is the only party selection rule that satisfies inclusion of direct winners and independence of definitely losing parties.

Axiom: Reinforcement for Winning Parties

If a party is selected for profile P_1 with threshold τ_1 and for profile P_2 with threshold τ_2 , then it should be selected for profile $P_1 + P_2$ with threshold $\tau_1 + \tau_2$.



DO









Characterization Theorem : DO is the only party selection rule that satisfies inclusion of direct winners and reinforcement for winning parties.

Axiom: Representative-strategyproofness

Voters cannot cause a party to be selected that they prefer to all currently selected parties by misreporting their preferences.

Axiom: Share-strategyproofness

Voters cannot cause a party to be selected that they prefer to all currently selected parties by misreporting their preferences *OR* increase the share of voters represented by their most-preferred selected party.

Incentive Issues



No hope for strategyproofness in general.

(Gibbard-Satterthwaite impossibility result applies since single-winner voting is a special case of our model)

Say that a party is (all with respect to a voter i)...

- ...Safe if it is always selected no matter how i votes.
- ...Risky if it might or might not be selected depending on how i votes.
- ...Out if it is always not selected no matter how *i* votes.

 $\ll au$ votes $\sim au$ votes $\gg au$ votes $\sim au$ votes $\sim au$ votes $\sim au$ votes $\sim au$ votes



Proposition : GP, MaxP and MaxR satisfy representative-strategyproofness when there is *at most one risky* party from the perspective of each voter. (DO and STV do not.)

 $<\!\!< au ext{ votes} > au ext{ votes} > au ext{ votes}$

Proposition: DO satisfies share-strategyproofness when every voter has a *safe party as one of their two most-preferred* parties. (GP, STV, MaxP and MaxR do not.)

In the (current) uninominal system, voters are incentivized to vote for their favorite party among the ones that will be selected:

32%
$$A > C$$
 32% $C > D > B$

 32% B
 4% $D > A$

 32% B
 32% B

 32% B
 4% $A > D$

 Represented

Proposition: DO and **GP** satisfy share-strategyproofness under the restriction that voters can only misreport by promoting their most-preferred *selected* party into first place. (STV, MaxP and MaxR do not)

Summary

	DO	STV	GP	MaxP	MaxR
Set-maximality				Ø	
Inclusion of direct winners					
Representation of solid coalitions					
Threshold monotonicity					
Ind. of definitely losing parties					
Ind. of clones					
Reinforcement for winning parties					
Monotonicity					
Rep-SP (one risky party)					
Share-SP (safe 1 st or 2 nd)					
Share-SP (rep. ranked 1st)					

6. Empirical Analysis

Context of the experiment

To collect appropriate preference data, we **ran a voting experiment** during the 2024 election of the French representative to the EU parliament.

Candidate parties: 38

Threshold: 5%

Parties above the threshold: 7

Lost votes: 12.1%



The experimental setup

- Explanation of the issues caused by the threshold.
- Presentation of the candidate lists.
- Vote with alternative voting methods.
- 4 Questionnaire.

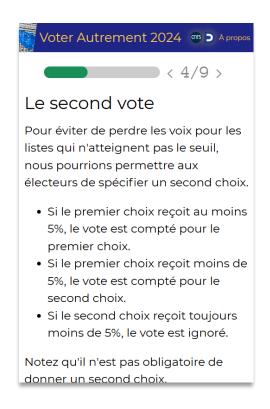


Fig. Screenshot of the website of the experiment conducted during the 2024 election of the French representative to the EU Parliament.

Two samples of participants

- 1
- Self-selected sample

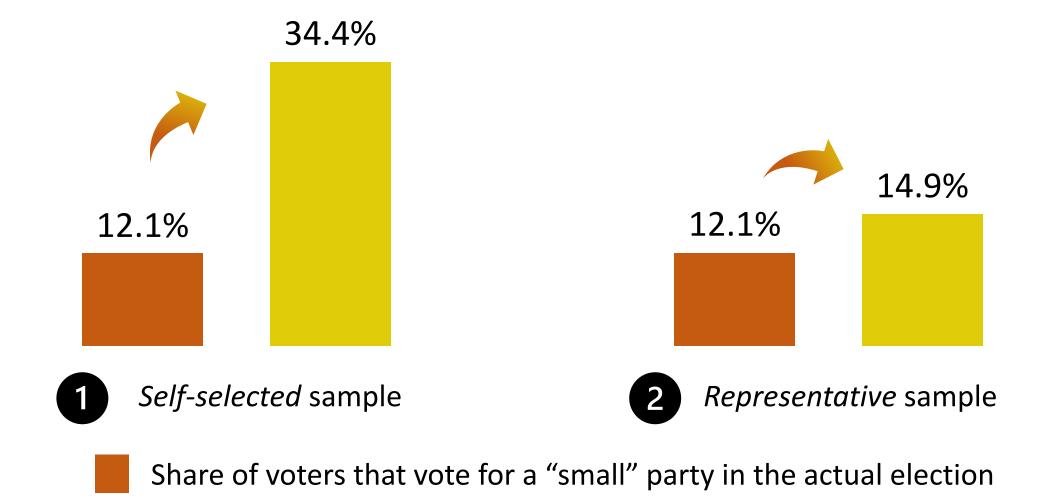
- 3 046 participants in a week.
- Recruited through social media, unpaid.
- Overrepresentation of leftwing, young and educated people.

2 Representative sample

- 1 000 participants.
- Recruited via a polling institute and paid a fixed amount to participate.
- Representative of the French population.

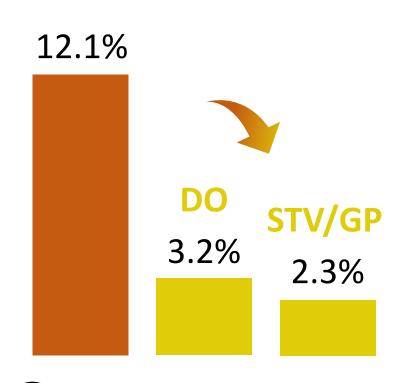


We assign weights to the voters to reduce the biases: weights are selected based on the vote of the participant at the actual election, to match the share of votes received by each party.

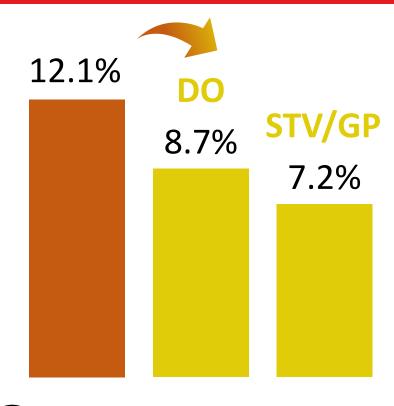


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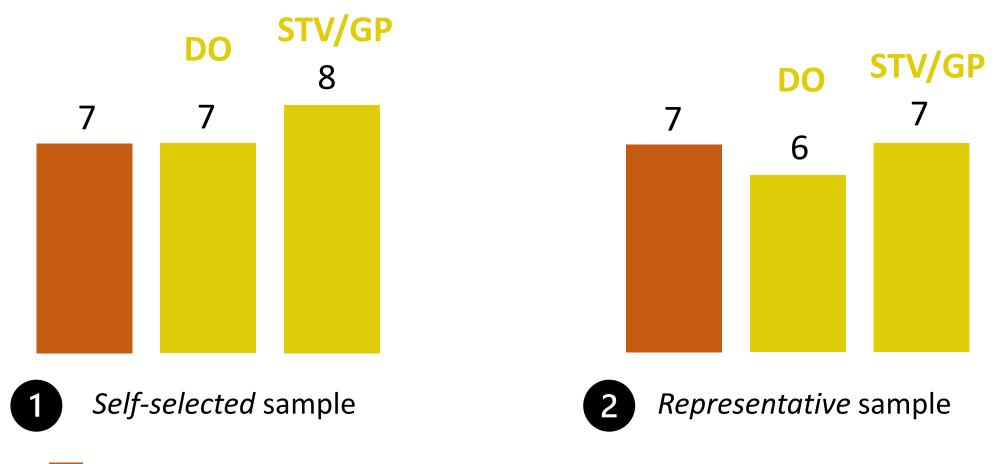
Share of voters that put a "small" party first in their ranking





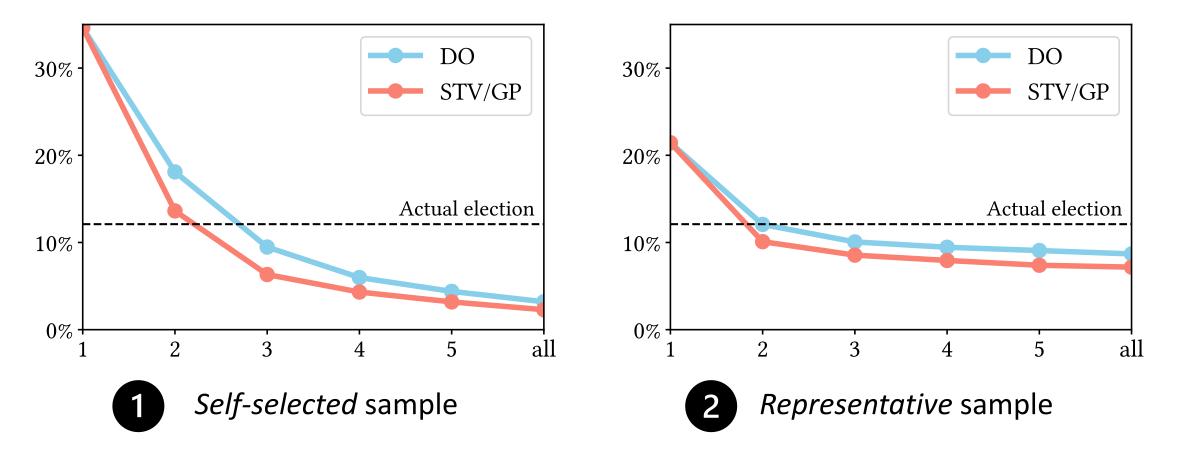


- 2 Representative sample
- Share of unrepresented voters in the actual election
- Share of unrepresented voters with ranking-based rules

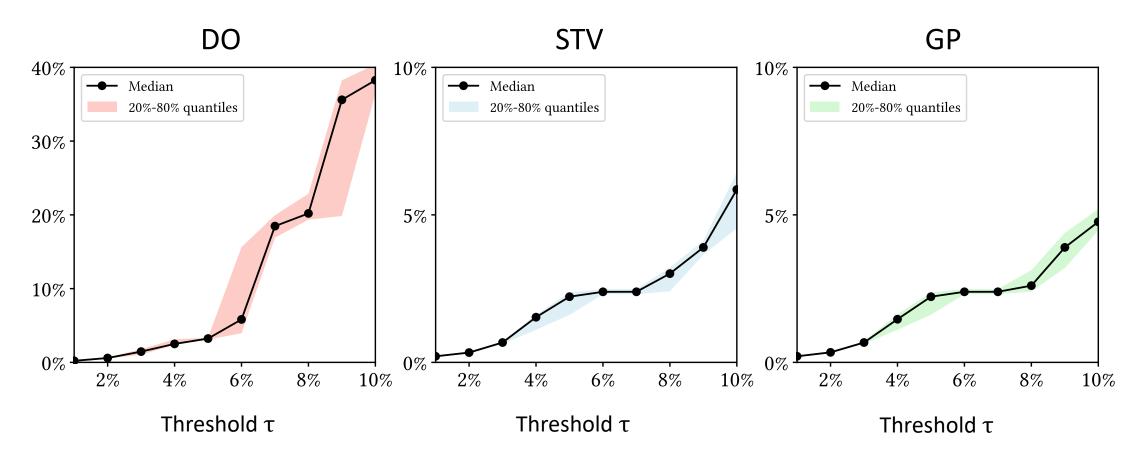


- Number of parties receiving a seat in the actual election
- Number of parties receiving a sear with ranking-based rules

4th Observation: we can ask for short rankings



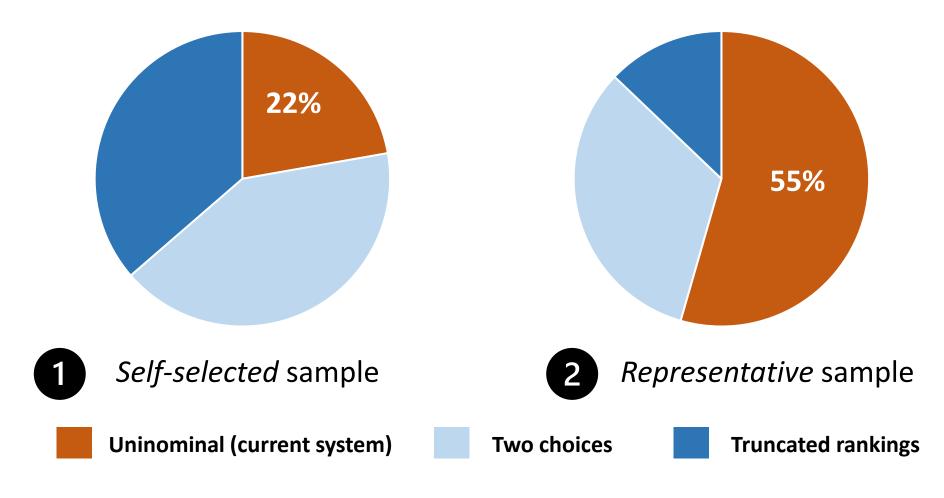
Share of unrepresented voters if all rankings are truncated to rank k (x-axis).



Share of unrepresented voters with different threshold values and with random noise added to the preferences (self-selected sample).

Opinion of the participants on the different systems

Which system do you think is better suited for the election of your representatives to the EU parliament?



Conclusion

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We axiomatically and empirically studied rules for electing parliaments with electoral thresholds.

Main takeaway: We can significantly increase representativeness by allowing voters to **rank** parties.

- STV and GP leave fewer voters unrepresented than DO.
- DO and GP have stronger strategyproofness guarantees than STV.
- STV satisfies independence of clones and represents solid coalitions.

Thanks for your attention! Questions?